

OS PROJECT INTERFACE: Java

STRUCTURE OF yourfile.java :

```
#include's      // These declarations (e.g. jobtable) exist only in your file, but
#define's       // since they lie outside of function definitions
typedef's       // they are global to the whole file and retain their
static variables // values over the course of program execution
                // (i. e., between function invocations).
```

```
void siodisk(int jobnum);
```

```
void siodrum(int jobnum, int jobsz, int coreaddress, int direction);
```

```
// Channel commands siodisk and siodrum are made available to you by the simulator.
// siodisk has one argument: job number, of type int and passed by value.
// siodrum has four arguments, all of type int and passed by value:
//     first argument is job number;
//     second argument is job size;
//     third argument is starting core address;
//     fourth argument is interpreted as follows:
//         1 => move from core (memory) to drum
//         0 => move from drum to core (memory)
```

```
void ontrace();      // called without arguments
```

```
void offtrace();     // called without arguments
```

```
// The 2 trace procedures allow you to turn the tracing mechanism on and off.
// The default value is off.  WARNING: ontrace produces a blow-by-blow description
// of each event and results in an extremely large amount of output.
// It should be used only as an aid in debugging.
// Even with the trace off, performance statistics are
// generated at regular intervals and a diagnostic message appears in case of a crash.
// In either case, your OS need not print anything.
```

```
void startup()
```

```
{
```

```
// Allows initialization of static system variables declared above.
// Called once at start of the simulation.
```

```
}
```

// INTERRUPT HANDLERS

```
// The following 5 functions are the interrupt handlers.  The arguments
// passed from the environment are detailed with each function below.
// See RUNNING A JOB, below, for additional information
```

```

void Crint (int []a, int []p)
{
    //  Indicates the arrival of a new job on the drum.
    //  At call: p [1] = job number
    //                p [2] = priority
    //                p [3] = job size, K bytes
    //                p [4] = max CPU time allowed for job
    //                p [5] = current time

}

```

```

void Dskint (int []a, int []p)
{
    //  Disk interrupt.
    //  At call: p [5] = current time
}

```

```

void Drmint (int []a, int []p)
{
    //  Drum interrupt.
    //  At call: p [5] = current time
}

```

```

void Tro (int [], int []p)
{
    //  Timer-Run-Out.
    //  At call: p [5] = current time
}

```

```

void Svc (int []a, int []p)
{
    //  Supervisor call from user program.
    //  At call: p [5] = current time
    //                a = 5 => job has terminated
    //                a = 6 => job requests disk i/o
    //                a = 7 => job wants to be blocked until all its pending
    //                        I/O requests are completed
}

```

Additional functions local to OS (scheduler, swapper, etc.)

RUNNING A JOB:

```

//  Before leaving each interrupt handler (with the return statement)
//  you must call the dispatcher to send info about which job to run.
//  The dispatcher should set the a and p arguments as follows:

```

```
//      a = 1  CPU is idle, p is ignored
//      a = 2  CPU is in user mode,
//              p [0], p [1], and p [5] are ignored
//              p [2] = base address of job to be run
//              p [3] = size (in K) of job to be run
//              p [4] = time quantum
```

NOTES:

- time is in milliseconds.
- core addresses are in K (0 - 99).
- priority ranges from 1 (highest) to 10 (lowest).
- assume interrupts are inhibited while OS is executing.

TO RUN SOS WITH YOUR OS:

compile yourfile.cpp separately and link with sos.obj (PC) or sos.o (Unix).
main() is defined in sos.

Look on the project Web site for individual "how-to" files for your compiler.